AOI's for J4TM

Revision Date:

Version 2.0 on June 23, 2017
Version 3.0 on Jan, 2018

Revision History

Name	Description
MCOM_MITSUBISHI	2.0 not exist 3.0 include the this AOI to communicate with servo drive 3.1 Adding a logic to read homed status of the drive
MMAFR Fault Reset	2.0 3.0 No change
MMAG Gearing	2.0 3.0 No change
MMAH Home	2.0 3.0 input data of speed command change to real data type with engineering unit capability 3.1 Adding the Homed status bit
MMAJ Jog	2.0 3.0 Input data of speed, acceleration, deceleration command change to real data type with engineering unit capability
MMAM Move	2.0 3.0 Input data of position, speed, acceleration, deceleration command change to real data type with engineering unit capability
MMAPT Move w/ Point Table	2.0 3.0 Remove
MMAPTEdit Point Table Edit	2.0 3.0 Remove
MMAR Arm Registration	2.0 3.0 The Touch probe capture value display in engineering unit. 3.1 Bug fix the engineer unit
MMAS Stop	2.0 3.0 No change
MMAD Shutdown	2.0 3.0 No change
MMASR Shutdown Reset	2.0 3.0 No change
MMAT Torque Move	2.0 3.0 Input of torque and speed limit value change to real data type and speed limit value can be set engineering unit.
MMAW Arm Watch	2.0 3.0 Input data of position command change to real data type with engineering unit capability 3.1 Bug fix the engineer unit
MMCFG Configuration	2.0 3.0 1) Rename the gear ratio setting input and change the data type real 2) Adding input variable unit setting, motor rated speed 3.1 Adding a logic when drive configure gearing to get the home status properly Change the decimal point of command position
MMDR Disarm Registration	2.0 3.0 No change

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MMDW Disarm watch	2.0 3.0 No change
MMRE Read Error	2.0 3.0 No change
MMReadP Read Parameters	2.0 3.0 No change
MMSF Servo Off	2.0 3.0 No change
MMSO Servo On	2.0 3.0 No change
MMWriteE Write Parameters to EEPROM	2.0 3.0 No change
MMWriteR Write Parameters to RAM	2.0 3.0 No change
MMRP Redefine the position	3.1 New AOI Added